## COMPLEXITY OF PROOF SEARCH

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## **PROOF COMPLEXITY**

## **Proof Search/Proof Size Estimation**



#### The Complexity of Theorem-Proving Procedures

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#### Summary

It is shown that any recognition problem solved by a polynomial timebounded nondeterministic Turing machine can be "reduced" to the problem of determining whether a given propositional formula is a tautology. Here "reduced" means, roughly speaking, that the first problem can be solved deterministically in polynomial time provided an oracle is available for solving the second. From this notion of reducible. polynomial degrees of difficulty are defined, and it is shown that the problem of determining tautologyhood has the same polynomial degree as the problem of determining whether the first of two given graphs is isomorphic to a subgraph of the second. Other examples are discussed. A method of measuring the complexity of proof procedures for the predicate calculus is introduced and discussed.

certain recursive set of strings on this alphabet, and we are interested in the problem of finding a good lower bound on its possible recognition times. We provide no such lower bound here. but theorem 1 will give evidence that {tautologies} is a difficult set to recognize, since many apparently difficult problems can be reduced to determining tautologyhood. By reduced we mean, roughly speaking, that if tautologyhood could be decided instantly (by an "oracle") then these problems could be decided in polynomial time. In order to make this notion precise, we introduce query machines, which are like Turing machines with oracles in [1].

A <u>query machine</u> is a multitape Turing machine with a distinguished tape called the <u>query tape</u>, and three distinguished states called the <u>query state</u>, <u>yes state</u>, and <u>no</u> state, respectively. If M is a

[Cook, 1971]: ACM STOC'71

The field of mechanical theorem proving badly needs a basis for comparing and evaluating the dozens of procedures which appear in the literature. Performance of a procedure on examples by computer is a good criterion, but not sufficient (unless the procedure proves useful in some practical way). A theoretical complexity criterion is needed which will bring out fundamental limita-

[Cook, 1971]: ACM STOC'71

## **Comparison by p-simulation**

[Reckhow 1975], [Cook-Reckhow 1974]



It's the kick off of proof complexity

Q and P proof systems for TAUT/UNSAT

## Def: Q p-simulates P iff there is a poly-time computable f such that if y is a P-proof of x, then f(y) is a Q-proof of x.

## **Resolution Inference Rule**



#### **Tree/Dag Proofs, Size, and Width**



## AUTOMATABILITY

## **Definition of automatability**

Def: P is AUTOMATABLE in time t(s) if an algorithm finds P-proofs in time t(s) the size s of smallest P-proof

[Bonet, Pitassi, Raz 97]

## **Proof size estimation problem**

# Fact: If P is automatable in time t(s), then optimal proof-size for P is t(s)-approximable (in time t(s)).

## $opt \leq estimate \leq t(opt)$

## CHARACTERIZATIONS OF PROOF MEASURES

## **Understanding Provability**

## Which F have (low complexity) refutations?

Which F do not have (low complexity) refutations?

Answer: Those that are "locally" satisfiable



Credit: Ascending and Descending by M. C. Escher, 1960













## The width-k Prover-Adversary game

Let F be a k-CNF with variables [n], let  $w \ge k+1$  an integer. Let  $M_w(n) = \{ \text{ partial truth assignments } f \text{ with } |f| \le w \}$ 

Prover and Adversary play a game:

- the positions are the f in  $M_w(n)$ ,
- query moves:

Prover queries a variable,

Adversary assigns a value,

- shrinking moves:

Prover suggests to discard some earlier assignments, Adversary happily accepts.



## The width-k Prover-Adversary game

Def: [Kolaitis-Vardi 2000], [A.-Dalmau 2004]

H is the winning region for Adversary

A winning strategy for Adversary in the width-w game on F is a set  $H \subseteq M_w(n)$  of partial truth assignments s.t.:

1) H is non-empty, 2) f in H  $\Rightarrow$  f is consistent with F, 3) f in H and g  $\subseteq$  f  $\Rightarrow$  g in H, 4) f in H, |Dom f| < w, x in F  $\Rightarrow$  ∃ b in {0,1} s.t. f U { x := b } in H.

#### **Characterizes Resolution Width**

Theorem: [A.–Dalmau 2004] Let F be a k-CNF. Let  $w \ge k+1$ . The following statements are equivalent:

1) there is no width-w Resolution refutation of F,

2) there is a winning strategy for Adversary in the width-w game on F.

Not a difficult theorem: just extremely useful...

IS THERE A GOOD CHARACTERIZATION OF RESOLUTION SIZE?

#### **The Size-Width Relationships**

Theorem: [Ben-Sasson-Wigderson 2001] Let F be a 3-CNF with n variables. Then:

$$2^{W(F)} \leq S_{\text{Tree}}(F) \leq n^{W(F)}$$
$$2^{cW(F)^2/n} \leq S_{\text{Dag}}(F) \leq n^{W(F)}$$

## Solving for W(F) ...

**Corollary**: Tree-like Resolution size is  $n^{O(\log s)}$ -approximable. **Corollary**: General Resolution size is  $n^{O(\sqrt{n \log s})}$  -approximable.

## **Tree-like Resolution**



#### **General Resolution**

Theorem [Ben-Sasson, Wigderson 99] Resolution is automatable in time  $n^{O(\sqrt{n \log s})}$ 

for s = poly(n), k = 3this is  $exp(n^{1/2} log(n)^{3/2})$ . Compare with ETH.



## Algorithm

Given F and s. Guess i and b and recurse on  $F[x_i=b]$  and s/2. Then recurse on  $F[x_i=1-b]$  and s-1.

> Subtle: Don't know if the guess that worked is the root of the optimal tree!



#### **Analysis**



Solution: n<sup>O(log s)</sup>

## FEASIBLE INTERPOLATION



INT(x) tells which one is unsatisfiable, for each given x.

### **Interpolants in graph theory**

CLIQUE<sub>k+1</sub>(x, y) := "y codes a k+1-clique of x" COL<sub>k</sub>(x, z) := "z codes a proper k-coloring of x" x codes a graph

## $CLIQUE_{k+1}(x, y) \land COL_k(x, z)$



## What are its interpolants?

"y is k+1-clique of x" ∧ "z is k-coloring of x"

$$\neg INT_{k}(x) \rightarrow ``\omega(x) \leq k''$$
$$INT_{k}(x) \rightarrow ``\chi(x) > k''$$
E.g. Lovász's Theta " $\vartheta(x) > k''$ 



 $ONE_i(x, y) \land ZERO_i(x, z)$ 

## What are its interpolants?

"f(y) = x and  $y_i = 1$ "  $\land$  "f(z) = x and  $z_i = 0$ "

$$\neg INT_{i}(x) \rightarrow "f^{-1}(x)_{i} = 0"$$

$$INT_{i}(x) \rightarrow "f^{-1}(x)_{i} = 1"$$
any interpolant inverts

the function (its i-th bit)

## **Feasible Interpolation**

**Def**: P has feasible interpolation:

all unsatisfiable  $F(x,y) \wedge G(x,z)$  have interpolants of circuit-size polynomial in the size of their smallest P-refutations.

[Krajicek 1997]

#### **Resolution has feasible interpolation**

## **Theorem:** [Krajicek 1997] Resolution has feasible interpolation.

#### **Interpolation algorithm: restrict & split**



## INTERPOLATION AND AUTOMATABILITY

#### **Automatability implies Interpolation**

Lemma: [Bonet, Pitassi, Raz 97] If a proof system is automatable, then it has feasible interpolation.



then this is an interpolant

proof system P

## **Strong systems lack feasible interpolation**

Theorem [Krajicek, Pudlak 98] Extended Frege does not have feasible interpolation unless RSA is broken by poly-size circuits

## **The Krajicek-Pudlak Argument**

The statements

"RSA<sub>i</sub>(y,k)=x and 
$$y_i = 1$$
"  $\wedge$  "RSA<sub>i</sub>(z,k)=x and  $z_i = 0$ "

#### have poly-size Extended Frege refutations.

Q.E.D.

#### **First Non-Automatability Result: EFrege**

## Corollary

## Extended Frege is not automatable unless RSA is invertible in poly-time

Well beyond resolution

Cryptographic assumption: I.e., hardness of NP ∩ co-NP ...

## SOUNDNESS PROOFS AND AUTOMATABILITY

#### **Interpolants of soundness statements**



## **Interpolants of soundness statements**

SAT(x, y)  $\land$  REF<sub>P,s</sub>(x, z)

# $\neg INT(x) \rightarrow \neg SAT(x, y)$ $INT(x) \rightarrow \neg REF_{P,s}(x, z)$

interpolant exists by the soundness of P

Sort of dual to what a SAT-solver does!

## SAT(x, y) $\land$ REF<sub>P,s</sub>(x, z)

If P is automatable then there is a poly-time interpolant

 $INT(x) := \neg REF_{P,p(s)}(x, A(x))$ 

polynomial runtime of automating algorithm automating algorithm of P



## Weak Automatability

**Theorem [Pudlák 2001]:** The following are equivalent:

(1) SAT & REF formulas for P have polytime interpolants
 (2) there exists an automatable Q that p-simulates P
 I.e., P is weakly automatable in Q

[A., Bonet 2003]

## **Resolution proofs of own soundness?**

Theorem [A., Bonet 2003] Resolution proofs of its own soundness must be of superpolynomial in size but poly-size Res(2)-proofs do exist!

Lower bound by reduction from CLIQUE & COL formulas

Resolution with 2-DNFs instead of clauses

AUTOMATING RESOLUTION IS HARD

## **The Alekhnovich-Razborov Theorem**

Theorem [Alekhnovich-Razborov 2001] Resolution is not automatable unless W[P] is tractable

- still relied on a strong assumption.
- best lower bound: time  $n^{\log\log(n)^{0.14}}$ , under ETH [Mertz-Pitassi-Wei 19]
- applies to tree-like Resolution!

## **Automating Resolution is NP-hard**

Theorem [A., Müller 2019] Resolution is not automatable in polynomial-time unless P = NP nor in subexponential-time unless ETH fails

- optimal assumption
- new method
- based on soundness proofs!

## A glimpse at the proof

## Find a map that takes CNFs into CNFs $F \xrightarrow{\text{polytime}} G$ **SMALL** F is sat $\implies$ min-size $(G) \le |G|^{1+\varepsilon}$ F is unsat $\implies$ min-size $(G) \le \exp(|G|^{\frac{1}{2}-\varepsilon})$ minimum Resolution BIG refutation size

The easy/hard formula



for poly length z

Upper bound : Uses the small soundness proof of Resolution in Res(2)! Lower bound : Adversary argument to mimic the exponentially big refutation.

## **Below/Beyond Resolution?**

Thm: [de Rezende'21] Tree-like Resolution is not automatable in less than quasipolynomial time unless ETH fails

F is sat  $\implies$  min-tree-size(G)  $\leq 2^{c\sqrt{N}}$ F is unsat  $\implies$  min-tree-size(G)  $\leq 2^{dN}$ 

## **THE BIG REMAING PROBLEM**

## Is Resolution Weakly Automatable?



THE END